

Commentary

Harnessing Light for Soft Microrobotics: Advances and Opportunities

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DESCRIPTION

Light-driven soft micro-robots based on hydrogels and Liquid Crystal Elastomers (LCEs) represent a fascinating intersection of soft robotics and materials science, offering exciting possibilities for a wide range of applications in fields such as biomedicine, environmental monitoring, and advanced manufacturing. These micro-robots, inspired by natural organisms like jellyfish and bacteria, harness the unique properties of hydrogels and LCEs to achieve locomotion and manipulation under light stimulus, paving the way for innovative solutions to complex challenges. Hydrogels are crosslinked polymer networks that can absorb and retain large amounts of water, resulting in soft, flexible materials with properties similar to biological tissues. Liquid crystal elastomers, on the other hand, are responsive materials that undergo reversible shape changes in response to external stimuli such as temperature, light, or mechanical force. By combining these two materials, researchers have developed light-driven soft micro-robots capable of complex movements and behaviors. The development of light-driven soft micro-robots begins with the fabrication of hydrogel-LCE composite structures with precise control over their morphology and mechanical properties. These structures can be designed to exhibit specific responses to light, such as bending, twisting, or swelling, depending on the composition and alignment of the materials. Light-responsive molecules or nanoparticles embedded within the hydrogel-LCE matrix further enhance their sensitivity to light, enabling fine-tuned control over micro-robot motion. One of the key advantages of light-driven soft micro-robots is their ability to achieve complex locomotion patterns with minimal external input. By selectively illuminating different regions of the micro-robot with light of varying intensity or wavelength, researchers can induce localized shape changes in the hydrogel-LCE composite, resulting in directed motion or manipulation. This light-driven actuation mechanism enables precise control over micro-robot movement, allowing them to navigate through complex environments and perform tasks with high dexterity. The unique properties of hydrogels and LCEs also make light-driven soft microrobots well-suited for biomedical applications, such as targeted drug

delivery, tissue engineering, and minimally invasive surgery. The soft, biocompatible nature of these materials reduces the risk of tissue damage or immune response when introduced into biological systems, making them ideal candidates for in vivo applications. Furthermore, the ability to remotely control micro-robot motion using light enables precise manipulation of biological tissues and structures with minimal invasiveness, opening up new possibilities for medical interventions. In addition to biomedical applications, light-driven soft micro-robots hold promise for environmental monitoring and remediation tasks, such as pollution detection, microscale assembly, and wastewater treatment. Their small size, flexibility, and responsiveness to light make them well-suited for navigating confined spaces and interacting with complex environmental matrices. By equipping these micro-robots with sensors, actuators, and other functional components, researchers can develop autonomous systems capable of monitoring environmental parameters, detecting contaminants, and performing targeted interventions to mitigate pollution and improve ecosystem health. Looking ahead, the prospects for light-driven soft micro-robots are bright, with ongoing research efforts focused on further enhancing their capabilities and expanding their range of applications. Advances in materials science, microfabrication techniques, and control algorithms are driving innovations in micro-robot design and performance, enabling the development of increasingly sophisticated systems with enhanced functionality and versatility. As our understanding of the interactions between light, materials, and micro-robot behavior continues to deepen, the potential for transformative applications in fields ranging from healthcare to environmental science will only continue to grow.

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CONFLICT OF INTEREST

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